

Math 3013  
Solutions to Problem Set 5

1. Determine which of the following mappings are linear transformations.

(a)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2 : T([x_1, x_2, x_3]) = [x_1 + x_2, x_1 - 3x_2]$

- This mapping is linear since if  $\mathbf{v} = [x_1, x_2, x_3]$

$$\begin{aligned} T(\lambda \mathbf{v}) &= T(\lambda [x_1, x_2, x_3]) \\ &= T([\lambda x_1, \lambda x_2, \lambda x_3]) \\ &= [\lambda x_1 + \lambda x_2, \lambda x_1 - 3\lambda x_2] \\ &= \lambda [x_1 + x_2, x_1 - 3x_2] \\ &= \lambda T([x_1, x_2, x_3]) \\ &= \lambda T(\mathbf{v}) \quad (T \text{ preserves scalar multiplication}) \end{aligned}$$

and if  $\mathbf{v} = [x_1, x_2, x_3]$  and  $\mathbf{v}' = [x'_1, x'_2, x'_3]$

$$\begin{aligned} T(\mathbf{v} + \mathbf{v}') &= T([x_1 + x'_1, x_2 + x'_2, x_3 + x'_3]) \\ &= [x_1 + x'_1 + x_2 + x'_2, x_1 + x'_1 - 3(x_2 + x'_2)] \\ &= [x_1 + x_2, x_1 - 3x_2] + [x'_1 + x'_2, x'_1 - 3x'_2] \\ &= T(\mathbf{v}) + T(\mathbf{v}') \quad (T \text{ preserves vector addition}) \end{aligned}$$

□

(b)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4 : T([x_1, x_2, x_3]) = [0, 0, 0, 0]$

- This mapping is linear since if  $\mathbf{v} = [x_1, x_2, x_3]$

$$\begin{aligned} T(\lambda \mathbf{v}) &= T([\lambda x_1, \lambda x_2, \lambda x_3]) \\ &= [0, 0, 0, 0] \\ &= \lambda [0, 0, 0, 0] \\ &= \lambda T([x_1, x_2, x_3]) \\ &= \lambda T(\mathbf{v}) \quad (T \text{ preserves scalar multiplication}) \end{aligned}$$

and if  $\mathbf{v} = [x_1, x_2, x_3]$  and  $\mathbf{v}' = [x'_1, x'_2, x'_3]$

$$\begin{aligned} T(\mathbf{v} + \mathbf{v}') &= T([x_1 + x'_1, x_2 + x'_2, x_3 + x'_3]) \\ &= [0, 0, 0, 0] \\ &= [0, 0, 0, 0] + [0, 0, 0, 0] \\ &= T(\mathbf{v}) + T(\mathbf{v}') \quad (T \text{ preserves vector addition}) \end{aligned}$$

□

(c)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4 : T([x_1, x_2, x_3]) = [1, 1, 1, 1]$

- This mapping is not linear since if  $\mathbf{v} = [x_1, x_2, x_3]$

$$\begin{aligned} T(\mathbf{v}) &= [1, 1, 1, 1] \\ T(2\mathbf{v}) &= [1, 1, 1, 1] \neq 2[1, 1, 1, 1] = 2T(\mathbf{v}) \end{aligned}$$

So the mapping does not preserve scalar multiplication.

□

(d)  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3 : T([x_1, x_2]) = [x_1 - x_2, x_2 + 1, 3x_1 - 2x_2]$

- This mapping is not linear since, e.g., if  $\mathbf{v} = [1, 1]$

$$\begin{aligned} T(\mathbf{v}) &= [0, 2, 1] \\ T(2\mathbf{v}) &= T([2, 2]) = [0, 3, 2] \neq [0, 4, 2] = 2T(\mathbf{v}) \end{aligned}$$

So the mapping does not preserve scalar multiplication.  $\square$

2. For each of the following, assume  $T$  is a linear transformation, from the data given, compute the specified value.

(a) Given  $T([1, 0]) = [3, -1]$ , and  $T([0, 1]) = [-2, 5]$ , find  $T([4, -6])$ .

- Because linear transformations preserve scalar multiplication and vector addition, they also preserve linear combinations:

$$T(c_1\mathbf{v}_1 + c_2\mathbf{v}_2) = c_1T(\mathbf{v}_1) + c_2T(\mathbf{v}_2)$$

Now take  $\mathbf{e}_1 = [1, 0]$  and  $\mathbf{e}_2 = [0, 1]$ . Then

$$\begin{aligned} T([4, -6]) &= T(4\mathbf{e}_1 - 6\mathbf{e}_2) \\ &= 4T(\mathbf{e}_1) - 6T(\mathbf{e}_2) \\ &= 4[3, -1] - 6[-2, 5] \\ &= [12 + 12, -4 - 30] \\ &= [24, -34] \end{aligned}$$

$\square$

(b) Given  $T([1, 0, 0]) = [3, 1, 2]$ ,  $T([0, 1, 0]) = [2, -1, 4]$ , and  $T([0, 0, 1]) = [6, 0, 1]$ , find  $T([2, -5, 1])$ .

- As in Part (a), we set  $\mathbf{e}_1 = [1, 0, 0]$ ,  $\mathbf{e}_2 = [0, 1, 0]$ , and  $\mathbf{e}_3 = [0, 0, 1]$  and then compute

$$\begin{aligned} T([2, -5, 1]) &= T(2\mathbf{e}_1 - 5\mathbf{e}_2 + \mathbf{e}_3) \\ &= 2T(\mathbf{e}_1) - 5T(\mathbf{e}_2) + T(\mathbf{e}_3) \\ &= 2[3, 1, 2] - 5[2, -1, 4] + [6, 0, 1] \\ &= [6 - 10 + 6, 2 + 5 + 0, 4 - 20 + 1] \\ &= [2, 7, -15] \end{aligned}$$

$\square$

3. Find the standard matrix representations of the following linear transformations.

(a)  $T([x_1, x_2]) = [x_1 + x_2, x_1 - 3x_2]$

- The standard matrix representations are computed by computing the action of the linear transformation  $T$  on the standard basis vectors, and then using results as the columns of the corresponding matrix. For the case at hand we have

$$\begin{aligned} \mathbf{e}_1 &= [1, 0] \Rightarrow T(\mathbf{e}_1) = [1 + 0, 1 - 3(0)] = [1, 1] \\ \mathbf{e}_2 &= [0, 1] \Rightarrow T(\mathbf{e}_2) = [0 + 1, 0 - 3(1)] = [1, -3] \end{aligned}$$

So the matrix corresponding to  $T$  is

$$\begin{bmatrix} 1 & 1 \\ 1 & -3 \end{bmatrix}$$

$\square$

(b)  $T([x_1, x_2, x_3]) = [x_1 + x_2 + x_3, x_1 + x_2, x_1]$

- We proceed as in Part (a).

$$\begin{aligned} \mathbf{e}_1 &= [1, 0, 0] \Rightarrow T(\mathbf{e}_1) = [1 + 0 + 0, 1 + 0, 1] = [1, 1, 1] \\ \mathbf{e}_2 &= [0, 1, 0] \Rightarrow T(\mathbf{e}_2) = [0 + 1 + 0, 0 + 1, 0] = [1, 1, 0] \\ \mathbf{e}_3 &= [0, 0, 1] \Rightarrow T(\mathbf{e}_3) = [0 + 0 + 1, 0 + 0, 0] = [1, 0, 0] \end{aligned}$$

So the matrix corresponding to  $T$  is

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

□

(c)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2 : T([x_1, x_2, x_3]) = [x_1 + x_2 + x_3, 2x_1 + 2x_2 + 2x_3]$

- We again compute the action of  $T$  on each standard basis vector  $\mathbf{e}_i$  in the domain  $\mathbb{R}^3$  of  $T$  and then use the results as the columns of  $\mathbf{A}_T$ :

$$\begin{aligned} \mathbf{e}_1 &= [1, 0, 0] \Rightarrow T(\mathbf{e}_1) = [1 + 0 + 0, 2 + 0 + 0] = [1, 2] \\ \mathbf{e}_2 &= [0, 1, 0] \Rightarrow T(\mathbf{e}_2) = [0 + 1 + 0, 0 + 2 + 0] = [1, 2] \\ \mathbf{e}_3 &= [0, 0, 1] \Rightarrow T(\mathbf{e}_3) = [0 + 0 + 1, 0 + 0 + 2, 0] = [1, 2] \end{aligned}$$

$$\mathbf{A}_T = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \end{bmatrix}$$

4. For each of the linear transformations  $T : \mathbb{R}^m \rightarrow \mathbb{R}^n$  in Problem 3, determine

$$\text{Range}(T) := \{\mathbf{y} \in \mathbb{R}^n \mid \mathbf{y} = T(\mathbf{x}) \text{ for some } \mathbf{x} \in \mathbb{R}^m\}$$

and

$$\text{Kernel}(T) := \{\mathbf{x} \in \mathbb{R}^m \mid T(\mathbf{x}) = \mathbf{0}_{\mathbb{R}^n}\} \quad .$$

- If the matrix corresponding to  $T$  is  $\mathbf{A}_T$ , then a basis for  $\text{Range}(T)$  coincides with a basis for the  $\text{ColSp}(\mathbf{A}_T)$  and a basis for  $\text{Kernel}(T)$  coincides with a basis for  $\text{NullSp}(\mathbf{A}_T)$ . These two bases, in turn, can be calculated by reducing  $\mathbf{A}_T$  to row echelon form and then interpreting that result accordingly. This I will do below for each of the matrices  $\mathbf{A}_T$  computed in Problem 3.

(a) Here we found

$$\mathbf{A}_T = \begin{bmatrix} 1 & 1 \\ 1 & -3 \end{bmatrix}$$

This matrix row reduces to the following Reduced Row Echelon Form.

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Because there is a pivot in each column of the RREF, each column of  $\mathbf{A}_T$  is a basis vector for  $\text{ColSp}(\mathbf{A}_T) \approx \text{Range}(T)$ . Thinking of  $\text{Range}(T)$  as a subspace of  $\mathbb{R}^2$ , and writing vectors in  $\mathbb{R}^2$  horizontally, we have

$$\text{ColSp}(\mathbf{A}_T) = \text{span} \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \end{bmatrix} \right) \Rightarrow \text{Range}(T) = \text{span}([1, 1], [1, -3])$$

Because there are no columns without pivots there are no free parameters in the solution of  $\mathbf{A}_T \mathbf{x} = \mathbf{0}$ . Therefore,  $\mathbf{x} = \mathbf{0}$  is the only solution and so  $\text{NullSp}(\mathbf{A}_T) = \{\mathbf{0}\}$ . Thus,

$$\text{Kernel}(T) = \text{NullSp}(\mathbf{A}_T) = \{\mathbf{0}\}$$

(b) Here we found

$$\mathbf{A}_T = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

This matrix row reduces to the following matrix in RREF

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Just like in part (a), there is a pivot in every column of the RREF and so each column of the original matrix is a basis vector for  $ColSp(\mathbf{A}_T) \approx Range(T)$ . Thus,

$$ColSp(\mathbf{A}_T) = span \left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right) \Rightarrow Range(T) = span([1, 1, 1], [1, 1, 0], [1, 0, 0])$$

Also, there are no free parameters in the solution set of  $\mathbf{A}_T \mathbf{x} = \mathbf{0}$ , and so

$$Kernel(T) \approx NullSp(\mathbf{A}_T) = \{\mathbf{0}\}$$

(c) Here we found

$$\mathbf{A}_T = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \end{bmatrix}$$

This matrix row reduces to the following RREF

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Since only the first column of the RREF contains a pivot, just the first column of  $\mathbf{A}_T$  will provide a basis for  $ColSp(\mathbf{A}_T) \approx Range(T)$ . Thus,

$$ColSp(\mathbf{A}_T) = span \left( \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right) \Rightarrow Range(T) = span([1, 2])$$

There are two columns without pivots, thus two free parameters  $x_2, x_3$  in the solution set of  $\mathbf{A}_T \mathbf{x} = \mathbf{0}$ . To get a basis for  $NullSp(\mathbf{A}_T) \approx Kernel(T)$ , we'll write down the general solution of  $\mathbf{A}_T \mathbf{x} = \mathbf{0}$  and grab the basis vectors from that. From the RREF form of  $\mathbf{A}_T$  we get the following equations

$$\left. \begin{array}{l} x_1 + x_2 + x_3 = 0 \\ 0 = 0 \end{array} \right\} \Rightarrow x_1 = -x_2 - x_3 \Rightarrow \mathbf{x} = \begin{bmatrix} -x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

And so

$$NullSp(\mathbf{A}_T) = span \left( \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right) \Rightarrow Kernel(T) = span([-1, 1, 0], [-1, 0, 1])$$

$$\begin{array}{rcl} x_1 + x_2 + x_3 & = & 0 \\ 0 & = & 0 \end{array}$$

5. If  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  is defined by  $T([x_1, x_2]) = [2x_1 + x_2, x_1, x_1 - x_2]$  and  $T' : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  is defined by  $T'([x_1, x_2, x_3]) = [x_1 - x_2 + x_3, x_1 + x_2]$ , find the standard matrix representation for the linear transformation  $T' \circ T$  that carries  $\mathbb{R}^2$  into  $\mathbb{R}^2$ . Find a formula for  $(T' \circ T)([x_1, x_2])$ .

- The matrix representations corresponding to  $T$  and  $T'$  are

$$\mathbf{M}_T = \begin{bmatrix} 2 & 1 \\ 1 & 0 \\ 1 & -1 \end{bmatrix}, \quad \mathbf{M}_{T'} = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

The matrix representation corresponding to  $T' \circ T$  will be given by the product of the corresponding matrices

$$\mathbf{M}_{T' \circ T} = \mathbf{M}_{T'} \mathbf{M}_T = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 0 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 3 & 1 \end{bmatrix}$$

Hence

$$(T' \circ T)(x_1, x_2) = [2x_1, 3x_1 + x_2]$$

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□