## BEHAVIOR OF SOLUTIONS OF 2D QUASI-GEOSTROPHIC EQUATIONS\*

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Abstract. We study solutions to the 2D quasi-geostrophic (QGS) equation

$$\frac{\partial \theta}{\partial t} + u \cdot \nabla \theta + \kappa (-\Delta)^{\alpha} \theta = f$$

and prove global existence and uniqueness of smooth solutions if  $\alpha \in (\frac{1}{2}, 1]$ ; weak solutions also exist globally but are proven to be unique only in the class of strong solutions. Detailed aspects of large time approximation by the linear QGS equation are obtained.

Key words. quasi-geostrophic equation, existence, uniqueness, large time approximation

AMS subject classifications. 76U05, 35Q35

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**1.** Introduction. This paper is concerned with the 2D surface quasi-geostrophic (QGS) equation

$$\frac{\partial \theta}{\partial t} + u \cdot \nabla \theta + \kappa (-\Delta)^{\alpha} \theta = f,$$

where  $\alpha \in [0, 1]$ ,  $\kappa > 0$ , and  $\theta = \theta(x, t)$  is a real scalar function of two space variables x and a time variable t. The velocity  $u = (u_1, u_2)$  is incompressible and determined from  $\theta$  by a stream function  $\psi$ :

(1.1) 
$$(u_1, u_2) = \left(-\frac{\partial \psi}{\partial x_2}, \frac{\partial \psi}{\partial x_1}\right),$$

and the stream function  $\psi$  satisfies

(1.2) 
$$(-\Delta)^{\frac{1}{2}}\psi = -\theta.$$

The nonlocal operator  $(-\Delta)^{\beta}$  ( $\beta \ge 0$ ) is defined through the Fourier transform

$$\widehat{(-\Delta)^{\beta}}f(\xi) = |\xi|^{2\beta}\widehat{f}(\xi),$$

where  $\widehat{f}$  is the Fourier transform of f [11]. For notational convenience, we write  $\Lambda$  for  $(-\Delta)^{\frac{1}{2}}$ .

The variable  $\theta$  in the 2D QGS equation represents the potential temperature, u is the fluid velocity, and the stream function  $\psi$  can be identified with the pressure. When the fractional power  $\alpha = 1/2$ , the equation, derived from the more general quasigeostrophic models (see pages 345–368 and 653–670 of [7]), describes the evolution

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of the temperature on the 2D boundary of a rapidly rotating half-space with small Rossby and Ekman numbers. Dimensionally, the 2D QGS equation with  $\alpha = 1/2$  is the analogue of the 3D Navier–Stokes equations. The general fractional power  $\alpha$  is considered here in order to observe the minimal power of Laplacian necessary in the analysis and thus make a comparison with the 3D Navier–Stokes equations [3], [6].

Recently, this equation has been intensively investigated because of both its mathematical importance and its potential for applications in meteorology and oceanography [4], [7], [5]. Mathematically, the behavior of solutions to the 2D QGS equation is strikingly similar to that of the potentially singular solutions to the 3D hydrodynamics equations. Despite exhibiting a number of similar features, the 2D QGS equation is considerably simpler than the 3D Euler or Navier–Stokes equations.

The smooth solution of the QGS equation is unique but, if  $\kappa = 0$ , it is known to exist only for a finite time [4]. On the other hand, weak solutions are global but their uniqueness is unknown [8]. Whether the smooth solution develops singularity in finite time and whether weak solutions are unique are fundamental mathematical issues related to the QGS equation. We show in section 2 that the solution remains smooth for all time for  $\alpha \in (\frac{1}{2}, 1]$  and any weak solution must coincide with a more regular solution as long as such a strong solution exists.

Large time behavior of weak solutions is investigated in sections 3 and 4. In section 3, the  $L^2$  decay rate of order  $t^{-\frac{1}{2\alpha}}$  is obtained. For generic initial data, this rate is optimal. The solution  $\theta$  of the nonlinear equation may be approximated by the solution  $\Theta$  of the linear equation with a higher-order correction. An explicit form for the higher-order correction is attempted in section 4. A rate of order  $t^{\frac{1}{2}-\frac{1}{\alpha}}$  is first obtained without any smoothness assumption. With the assumption that

$$\|\Lambda^{2-2\alpha+\delta}\theta(\cdot,t)\|_{L^2} \sim t^{-\epsilon},$$

the ratio and the difference are shown to behave as follows:

$$\frac{\|\theta(\cdot,t)\|_{L^2}}{\|\Theta(\cdot,t)\|_{L^2}} \sim 1 + O(t^{-\min\{\frac{1}{2\alpha},\epsilon\}}), \quad \|\theta(\cdot,t) - \Theta(\cdot,t)\|_{L^2} \sim t^{-\frac{1}{2\alpha}-\min\{\frac{1}{2\alpha},\epsilon\}},$$

which imply that the effect of the nonlinearity is felt only in the higher-order correction.

We conclude this introduction by mentioning the global existence result of weak solutions obtained in [8]. When not specified, the spatial domain can be either the whole  $\mathbb{R}^2$  or the 2D torus  $\mathbb{T}^2$ .

PROPOSITION 1.1. Let T > 0 be arbitrary. Then for every  $\theta_0 \in L^2$  and  $f \in L^2([0,T]; H^{-\alpha})$ , there exists a weak solution of

(1.3) 
$$\partial_t \theta + u \cdot \nabla \theta + \kappa \Lambda^{2\alpha} \theta = f,$$

(1.4) 
$$\theta|_{t=0} = \theta_0$$

which satisfies

$$\theta \in L^{\infty}([0,T];L^2) \cap L^2([0,T];H^{\alpha}).$$

2. Global smooth solution and uniqueness. It is shown here that weak solutions of the QGS equation are globally smooth for  $\alpha \in (\frac{1}{2}, 1]$  and "strong" solutions are unique. The spatial domain here is the 2D torus  $\mathbb{T}^2$ .

THEOREM 2.1. Let  $\alpha \in (\frac{1}{2}, 1]$ ,  $\beta \geq 0$ , and  $\beta + 2\alpha > 2$ . If  $\theta_0 \in H^{\beta}(\mathbb{T}^2)$  and if, for T > 0,

$$f \in L^2([0,T]; H^{\beta-\alpha}), \quad \int_0^T \|f(\tau)\|_{L^q} d\tau < \infty,$$

where  $q = \infty$  for  $\beta \ge 1$  and  $q = 2/(1 - \beta)$  for  $\beta < 1$ , then the solution  $\theta$  of (1.3) and (1.4) obeys for all  $t \le T$ 

(2.1) 
$$\|\Lambda^{\beta}\theta(t)\|_{L^{2}} \leq C,$$

where C is constant depending only on T,  $\|\theta_0\|_{H^{\beta}}$ ,  $\|f\|_{L^2([0,T];H^{\beta-\alpha})}$ , and  $\int_0^T \|f(\tau)\|_{L^q} d\tau$ . Proof. We sketch the proof. Taking the scalar product of (1.3) with  $\Lambda^{2\beta}\theta$ 

$$\frac{1}{2}\frac{d}{dt}\int|\Lambda^{\beta}\theta|^{2}+\kappa\int|\Lambda^{\alpha+\beta}\theta|^{2}=-\int(u\cdot\nabla\theta)\Lambda^{2\beta}\theta+\int\Lambda^{2\beta}\theta f$$

and using the estimates

(2.2) 
$$\left|\int \Lambda^{2\beta} \theta f\right| \leq \frac{\kappa}{4} \|\Lambda^{\alpha+\beta} \theta\|_{L^2}^2 + \frac{1}{\kappa} \|\Lambda^{\beta-\alpha} f\|_{L^2}^2,$$

(2.3) 
$$\left| \int (u \cdot \nabla \theta) \Lambda^{2\beta} \theta \right| \leq \frac{\kappa}{4} \|\theta\|_{H^{\alpha+\beta}}^2 + C(\kappa, \theta_0, f) \|\theta\|_{H^{\beta}}^2,$$

where  $C(\kappa, \theta_0, f)$  is constant, we obtain (2.1) after applying Gronwall's inequality. The estimate (2.3) is obtained by using the calculus inequality (see page 61 of [8] and inequality (3.1.59) on page 74 of [12])

$$\|\Lambda^{s}(gh)\|_{L^{2}} \leq C(\|g\|_{L^{q}}\|\Lambda^{s}h\|_{L^{p}} + \|h\|_{L^{q}}\|\Lambda^{s}g\|_{L^{p}})$$

with 1/p + 1/q = 1/2, g = u,  $h = \theta$ ,  $s = \beta + 1 - \alpha$ , and the maximum principle

$$\|\theta\|_{L^q} \le \|\theta_0\|_{L^q} + \int_0^t \|f(\tau)\|_{L^q} d\tau.$$

Although weak solutions may not be unique, there is at most one solution in the class of "strong" solutions.

THEOREM 2.2. Assume that  $\alpha \in (\frac{1}{2}, 1]$ , T > 0, p and q satisfy

(2.4) 
$$p \ge 1, \quad q > 0, \qquad \frac{1}{p} + \frac{\alpha}{q} = \alpha - \frac{1}{2};$$

then there is at most one solution  $\theta$  of the QGS equation with initial data  $\theta_0 \in L^2$  such that

(2.5) 
$$\theta \in L^{\infty}([0,T]; L^2) \cap L^2([0,T]; H^{\alpha}),$$

(2.6) 
$$\theta \in L^q([0,T];L^p).$$

We make two remarks.

Remark 2.3. It is clear from the proof given below that we can assume that only one of the two solutions is "strong," i.e., in the class (2.5), (2.6), the other being only a weak solution.

Remark 2.4. By taking  $\alpha = 1$ , (2.6) with (2.4) reduces exactly to the regularity assumptions in obtaining uniqueness for weak solutions to the 3D Navier–Stokes equations (cf. Temam [13, p. 299]). Theorem 2.2 is a sort of generalization in the sense that it holds for a range of  $\alpha \in (\frac{1}{2}, 1]$ .

Proof of Theorem 2.2. The difference  $\theta = \theta_A - \theta_B$  of two solutions  $\theta_A$  and  $\theta_B$  satisfies

(2.7) 
$$\partial_t \theta + u \cdot \nabla \theta_A + u_B \cdot \nabla \theta + \kappa \Lambda^{2\alpha} \theta = 0$$

in which  $u = u_A - u_B$  with  $u_A$  and  $u_B$  being the velocities corresponding to  $\theta_A$  and  $\theta_B$ . We take the scalar product of (2.7) with  $\psi = -\Lambda^{-1}\theta$  and use

$$\int_{\mathbb{T}^2} \psi u \cdot \nabla \theta_A = 0,$$

$$\left| \int_{\mathbb{T}^2} \theta u_B \cdot \nabla \psi \right| \le \kappa \|\psi\|_{H^{\alpha+\frac{1}{2}}}^2 + C(\kappa) \|\theta_B\|_{L^p}^{\frac{1}{1-\beta}} \|\psi\|_{H^{\frac{1}{2}}}^2$$

where  $\beta = \frac{1}{\alpha} \left( \frac{1}{2} + \frac{1}{p} \right)$  and  $C(\kappa) = C \kappa^{-\frac{\beta}{1-\beta}}$  (see page 32 of [8]). It then follows that

$$\frac{d}{dt} \|\psi\|_{H^{\frac{1}{2}}}^2 \le C(\kappa) \|\theta_B\|_{L^p}^{\frac{1}{1-\beta}} \|\psi\|_{H^{\frac{1}{2}}}^2,$$

which implies that  $\psi = 0$  and thus  $\theta = 0$ .

**3. Large time behavior.** The large time behavior of weak solutions is investigated in this section. We adapt well-known ideas of Amick, Bona, and Schonbek [1] and Schonbek [9], [10].

We first analyze the case when the force f = 0 and the result can be stated as follows.

THEOREM 3.1. Let  $\alpha \in (0,1]$  and  $\theta_0 \in L^1(\mathbb{R}^2) \cap L^2(\mathbb{R}^2)$ . Then there exists a weak solution  $\theta$  of the 2D QGS equation

(3.1) 
$$\partial_t \theta + u \cdot \nabla \theta + \Lambda^{2\alpha} \theta = 0, \qquad \theta |_{t=0} = \theta_0$$

such that

(3.2) 
$$\|\theta(\cdot,t)\|_{L^2(\mathbb{R}^2)} \le C(1+t)^{-\frac{1}{2\alpha}},$$

where C is a constant depending on  $L^1$  and  $L^2$  norms of  $\theta_0$ .

*Remark* 3.2. For generic initial data, the rate obtained in Theorem 3.1 is optimal, as implied by Theorem 4.6 of section 4.

The proof of Theorem 3.1 consists of two major steps. The first step is a formal argument to show that (3.2) holds for smooth solutions. In the second step the formal argument is applied to a sequence of "retarded mollifications" [2] and we obtain Theorem 3.1 after passing to the limit. We will need a simple estimate.

LEMMA 3.3. Assume that  $\theta_0 \in L^1(\mathbb{R}^2) \cap L^2(\mathbb{R}^2)$ . Then  $\theta$  satisfies the a priori estimate

$$|\widehat{\theta}(\xi,t)| \le \|\theta_0\|_{L^1} + |\xi| \int_0^t \|\theta(\tau)\|_{L^2}^2 d\tau.$$

*Proof.* We have from (3.1)

(\*) 
$$\partial_t \hat{\theta} + |\xi|^{2\alpha} \hat{\theta} = -\widehat{u \cdot \nabla \theta}.$$

Since  $\nabla \cdot u = 0$ ,

$$|\widehat{u \cdot \nabla \theta}| \le |\xi| \|\theta(t)\|_{L^2}^2.$$

After integrating (\*), we obtain

$$|\widehat{\theta}(\xi,t)| \le |\widehat{\theta_0}(\xi)| + |\xi| \int_0^t \|\theta(\tau)\|_{L^2}^2 d\tau \le \|\theta_0\|_{L^1} + |\xi| \|\theta_0\|_{L^2}^2 t.$$

Proof of Theorem 3.1. Taking the scalar product of (3.1) with  $\theta$  we obtain

$$\frac{1}{2}\frac{d}{dt}\int_{\mathbb{R}^n}|\theta|^2+\int_{\mathbb{R}^n}\left(\Lambda^{\alpha}\theta\right)^2=0.$$

Using Plancherel's theorem,

$$\frac{d}{dt}\int_{\mathbb{R}^2}|\widehat{\theta}|^2 + 2\int_{\mathbb{R}^2}|\xi|^{2\alpha}|\widehat{\theta}|^2 = 0$$

For the second term

$$\begin{split} \int_{\mathbb{R}^2} |\xi|^{2\alpha} |\widehat{\theta}|^2 &\geq \int_{B(t)^c} |\xi|^{2\alpha} |\widehat{\theta}|^2 \geq g^{2\alpha}(t) \int_{B(t)^c} |\widehat{\theta}|^2 \\ &= g^{2\alpha}(t) \int_{\mathbb{R}^2} |\widehat{\theta}|^2 - g^{2\alpha}(t) \int_{B(t)} |\widehat{\theta}|^2, \end{split}$$

where  $g \in C([0,\infty);\mathbb{R}^+)$  remains to be determined and  $B(t)^c$  is the complement of B(t) with

$$B(t) = \{ \xi \in \mathbb{R}^2 : |\xi| < g(t) \}.$$

By Lemma 3.3, we obtain

$$\frac{d}{dt}\int_{\mathbb{R}^2}|\widehat{\theta}|^2+2g^{2\alpha}(t)\int_{\mathbb{R}^2}|\widehat{\theta}|^2$$

(3.3) 
$$\leq 2\pi g^{2\alpha}(t) \int_0^{g(t)} \left[ \|\theta_0\|_{L^1} + r \int_0^t \|\theta(\tau)\|_{L^2}^2 d\tau \right]^2 r dr.$$

By integrating (3.3), we have

$$e^{2\int_0^t g^{2\alpha}(\tau)d\tau} \int_{\mathbb{R}^2} |\widehat{\theta}|^2 \le \|\theta_0\|_{L^2}^2$$

(3.4) 
$$+ \int_0^t e^{2\int_0^s g^{2\alpha}(\tau)d\tau} \left[ C_1 g^{2\alpha+2}(s) + C_2 s g^{2\alpha+4}(s) \int_0^s \|\theta(\tau)\|_{L^2}^4 d\tau \right] ds,$$

where  $C_1 = 2\pi \|\theta_0\|_{L^1}^2$  and  $C_2 = \pi$ . To obtain a basic estimate, we take  $g^{2\alpha}(t) = \left(\frac{1}{2} + \frac{1}{2\alpha}\right) \left[(e+t)\ln(e+t)\right]^{-1}$  and thus  $e^{2\int_{0}^{t}g^{2\alpha}(\tau)d\tau} = [\ln(e+t)]^{(1+\frac{1}{\alpha})}$ . We then obtain from (3.4)

$$\|\theta\|_{L^2}^2 \le C[\ln(e+t)]^{-1-\frac{1}{\alpha}}$$

To obtain the sharp decay result, we take  $g^{2\alpha}(t) = \frac{1}{2\alpha(t+1)}$  and thus  $e^{2\int_0^t g^{2\alpha}(\tau)d\tau} =$  $(1+t)^{\frac{1}{\alpha}}$ . From (3.4),

$$\|\theta(t)\|_{L^2}^2 \le C(t+1)^{-\frac{1}{\alpha}} + C(t+1)^{(1-\frac{2}{\alpha})} \int_0^t \|\theta(s)\|_{L^2}^2 [\ln(e+s)]^{-1-\frac{1}{\alpha}} ds.$$

Using Gronwall's inequality and the fact that  $\alpha \leq 1$ ,

(3.5) 
$$\|\theta(t)\|_{L^2}^2 \le C(1+t)^{-\frac{1}{\alpha}},$$

where the constant C depends on the  $L^1$  and  $L^2$  norms of  $\theta_0$ . We note here that (3.5) is actually obtained by first taking  $g^{2\alpha}(t) = \left(\frac{1}{2\alpha} - \epsilon\right) \frac{1}{1+t}$  and then passing to the limit as  $\epsilon \to 0$ . This completes the formal argument step.

Next we construct a sequence of retarded mollifications  $\theta_n$  and carry over the formal arguments to  $\theta_n$ . We will present here only the main ideas. We approximate the QGS equation by a sequence of equations

(3.6) 
$$\partial_t \theta_n + u_n \cdot \nabla \theta_n + \Lambda^{2\alpha} \theta_n = 0,$$

where  $\delta_n \to 0$  and  $u_n = S_{\delta_n}(\theta_n)$  is obtained from  $\theta_n$  by

$$S_{\delta_n}(\theta_n) = \int_0^\infty \phi(\tau) \mathcal{R}^\perp \theta_n(t - \delta_n \tau) d\tau.$$

We denote here  $\mathcal{R}^{\perp} = (-\partial_{x_2}\Lambda, \partial_{x_1}\Lambda)$  as the Riesz transform. The smooth function  $\phi$  is nonnegative with compact support in [1,2] and  $\int_0^{\infty} \phi(t) dt = 1$ . For each n, (3.6) is a linear equation since the values of  $u_n(t)$  depend only on the values of  $\theta_n$  in  $[t-2\delta_n,t-\delta_n].$ 

Without giving details, we point out that  $\theta_n$  converges to a weak solution  $\theta$ strongly in  $L^2$  for almost every t. Hence

$$\|\theta(t)\|_{L^2} \le \|\theta_n(t) - \theta(t)\|_{L^2} + \|\theta_n(t)\|_{L^2} \le C(1+t)^{-\frac{1}{2\alpha}},$$

where C is a constant depending only on the  $L^1$  and  $L^2$  norms of  $\theta_0$ . This completes the proof of Theorem 3.1. Π

We now consider the case when the force f is not zero.

THEOREM 3.4. Let  $\alpha \in (0,1]$  and  $\theta_0 \in L^1(\mathbb{R}^2) \cap L^2(\mathbb{R}^2)$ . Assume that  $f \in L^1([0,\infty); L^2)$ , satisfying

(3.7) 
$$||f(\cdot,t)||_{L^2} \le C(1+t)^{-\frac{1}{\alpha}-1}, \qquad |\widehat{f(\xi,t)}| \le C|\xi|^{\alpha}$$

for some constant C. Then there is a weak solution of the QGS equation

$$\partial_t \theta + u \cdot \theta + \Lambda^{2\alpha} \theta = f$$

such that

(3.8) 
$$\|\theta(\cdot,t)\|_{L^2} \le C(1+t)^{-\frac{1}{2\alpha}}$$

*Proof.* The arguments of Theorem 3.1 work here and we will point out only the difference. It is easy to see that

$$\|\theta(t)\|_{L^2} \le \|\theta_0\|_{L^2} + \int_0^t \|f(\tau)\|_{L^2} d\tau \le C$$

by energy estimates. When the force f is present, the estimate for  $\hat{\theta}$  is given by

$$\widehat{\theta}(\xi,t)| \leq e^{-|\xi|^{2\alpha}t} |\widehat{\theta_0}| + \int_0^t e^{-|\xi|^{2\alpha}(t-\tau)} \left[\widehat{f} + |\xi| \|\theta\|_{L^2}^2\right] d\tau.$$

Then the procedures of the proof of Theorem 3.1 can be repeated and the assumptions (3.7) are sufficient in establishing (3.8).

4. Large time approximation. In this section we intend to understand the higher-order correction in the large time approximation of the solution  $\theta$  to the non-linear equation by the solution  $\Theta$  to the linear equation. The approach is to study the difference and the ratio

$$\|\theta(\cdot,t) - \Theta(\cdot,t)\|_{L^2}, \qquad \frac{\|\theta(\cdot,t)\|_{L^2}}{\|\Theta(\cdot,t)\|_{L^2}}.$$

We start with some estimates for the linear equation. The solution of the linear equation on  $\mathbb{R}^n$ 

(4.1) 
$$\partial_t \theta + \Lambda^{2\alpha} \theta = 0, \qquad \theta \mid_{t=0} = \theta_0$$

is given by

(4.2) 
$$\Theta(t) = k_t^{\alpha} * \theta_0,$$

where the kernel  $k_t^{\alpha}$  is defined by its Fourier transform

(4.3) 
$$\widehat{k}_t^{\alpha}(\xi) = e^{-|\xi|^{2\alpha}t}.$$

PROPOSITION 4.1. Assume that  $\alpha > 0$  and the initial data  $\theta_0 \in L^1(\mathbb{R}^n)$ . Then we have

(4.4) 
$$\lim_{t \to \infty} t^{\frac{n}{2\alpha}} \|\Theta(\cdot, t)\|_{L^2}^2 = A(n, \alpha) \left[ \int_{\mathbb{R}^n} \theta_0(x) dx \right]^2,$$

(4.5) 
$$\lim_{t \to \infty} t^{\frac{n+2}{2\alpha}} \|\nabla \Theta(\cdot, t)\|_{L^2}^2 = B(n, \alpha) \left[ \int_{\mathbb{R}^n} \theta_0(x) dx \right]^2,$$

where the constants  $A(n, \alpha) = \int_{\mathbb{R}^n} e^{-2|\eta|^2} d\eta$  and  $B(n, \alpha) = \int_{\mathbb{R}^n} |\eta|^2 e^{-2|\eta|^2} d\eta$ . Especially for n = 2, the  $L^2$  decay rates of  $\Theta$  and  $\nabla \Theta$  are  $t^{-\frac{1}{2\alpha}}$  and  $t^{-\frac{1}{\alpha}}$ , respectively.

Especially for n = 2, the L accuy rules of  $\Theta$  and  $\nabla \Theta$  are  $t^{-2\alpha}$  and  $t^{-\alpha}$ , respectively.

*Proof.* We first prove (4.4). By Plancherel's theorem,

$$\lim_{t \to \infty} t^{\frac{n}{2\alpha}} \|\Theta(\cdot, t)\|_{L^2}^2 = \lim_{t \to \infty} t^{\frac{n}{2\alpha}} \|\widehat{\Theta}(\cdot, t)\|_{L^2}^2$$

$$=\lim_{t\to\infty}t^{\frac{n}{2\alpha}}\int_{\mathbb{R}^n}e^{-2|\xi|^{2\alpha}t}|\widehat{\theta}_0|^2(\xi)d\xi=\lim_{t\to\infty}\int_{\mathbb{R}^n}e^{-2|\eta|^2}|\widehat{\theta}_0|^2(\eta t^{-\frac{1}{2\alpha}})d\eta.$$

Since for any  $t \in [0, \infty)$ 

$$\int_{\mathbb{R}^n} e^{-2|\eta|^2} |\widehat{\theta}_0|^2 (\eta t^{-\frac{1}{2\alpha}}) d\eta$$

$$\leq \|\widehat{\theta}_0\|_{L^{\infty}}^2 \int_{\mathbb{R}^n} e^{-2|\eta|^2} d\eta \leq A(n,\alpha) \|\theta_0\|_{L^1}^2,$$

we can apply the dominated convergence theorem, which leads to (4.4).

The proof of (4.5) is similar to that of (4.4). We have

$$\lim_{t \to \infty} t^{\frac{n+2}{\alpha}} \|\nabla \Theta(\cdot, t)\|_{L^2}^2 = \lim_{t \to \infty} t^{\frac{n+2}{\alpha}} \int_{\mathbb{R}^n} |\xi|^2 e^{-2|\xi|^{2\alpha}t} |\widehat{\theta}_0|^2(\xi) d\xi$$
$$= \lim_{t \to \infty} \int_{\mathbb{R}^n} |\eta|^2 e^{-2|\eta|^2} |\widehat{\theta}_0|^2(\eta t^{-\frac{1}{2\alpha}}) d\eta = B(n, \alpha) \left[ \int_{\mathbb{R}^n} \theta_0(x) dx \right]^2. \quad \Box$$

PROPOSITION 4.2. Let  $\alpha \in (0,1]$  and  $\theta_0 \in L^2(\mathbb{R}^2)$ . Then the solution  $\Theta$  of (4.1) satisfies

$$\|\nabla\Theta(t)\|_{L^{\infty}(\mathbb{R}^2)} \le Ct^{-\frac{1}{\alpha}}.$$

where the constant C depends only on the  $L^2$  norm of  $\theta_0$ .

*Proof.* We have by (4.2) and (4.3)

$$\|\nabla \Theta\|_{L^{\infty}} \le \int_{\mathbb{R}^2} |\xi| |\widehat{\Theta}(\xi)| d\xi = \int_{\mathbb{R}^2} |\xi| e^{-|\xi|^{2\alpha} t} |\widehat{\theta}_0(\xi)| d\xi$$

$$\leq \|\theta_0\|_{L^2} \left( \int_{\mathbb{R}^2} |\xi|^2 e^{-2|\xi|^{2\alpha} t} d\xi \right)^{\frac{1}{2}} \leq C \left( \int_0^\infty r^3 e^{-2r^{2\alpha} t} dr \right)^{\frac{1}{2}} \leq C t^{-\frac{1}{\alpha}},$$

where the constant C depends only on the  $L^2$  norm of  $\theta_0$ .

THEOREM 4.3. Let  $\alpha \in (0,1]$  and  $\theta_0 \in L^1(\mathbb{R}^2) \cap L^2(\mathbb{R}^2)$ . Then the difference  $\theta - \Theta$  between a weak solution  $\theta$  of the QGS equation and the solution  $\Theta$  of the linear QGS equation with the data  $\theta_0$  satisfies

4

$$\|\theta(t) - \Theta(t)\|_{L^2(\mathbb{R}^2)} \le C(1+t)^{\frac{1}{2} - \frac{1}{\alpha}},$$

where the constant C depends only on the  $L^1$  and  $L^2$  norms of  $\theta_0$ .

Remark 4.4. By comparing the rates in Theorems 3.1 and 4.3, we see that  $\theta - \Theta$  decays faster than  $\theta$  does for large time for  $\alpha < 1$ .

*Proof.* We will present only a formal argument. The justification process can be done similarly as in the proof of Theorem 3.1. The difference  $w = \theta - \Theta$  satisfies

(4.6) 
$$\partial_t w + \Lambda^{2\alpha} w = -u \cdot \nabla \theta.$$

Taking the scalar product of (4.6) with w and using the fact that

$$\int_{\mathbb{R}^2} (u \cdot \nabla \theta) \theta dx = 0,$$

we obtain

$$\frac{d}{dt}\int_{\mathbb{R}^2}|w|^2+2\int_{\mathbb{R}^2}|\Lambda^{\alpha}w|^2=\int_{\mathbb{R}^2}\Theta(u\cdot\nabla\theta)dx.$$

Using the results of Proposition 4.2 and Theorem 3.1, we bound the right-hand term by

$$\left| \int_{\mathbb{R}^2} \Theta(u \cdot \nabla \theta) dx \right| \le \| \nabla \Theta \|_{L^{\infty}} \| \theta \|_{L^2}^2 \le C(1+t)^{-\frac{2}{\alpha}}.$$

As in the proof of Theorem 3.1,

(4.7) 
$$\frac{d}{dt} \int_{\mathbb{R}^2} |\widehat{w}|^2 + 2g^{2\alpha}(t) \int_{\mathbb{R}^2} |\widehat{w}|^2 \le 2g^{2\alpha}(t) \int_{|\xi| \le g(t)} |\widehat{w}|^2 + C(1+t)^{-\frac{2}{\alpha}},$$

where g(t) remains to be decided.

We need an estimate of  $\hat{w}$ , which can be obtained by taking the Fourier transform of (4.6) and proceeding as in Lemma 3.3. By Theorem 3.1 and noticing  $\alpha \leq 1$ ,

$$|w(\xi,t)| \le |\xi| \int_0^t \|\theta(\tau)\|_{L^2}^2 d\tau \le |\xi| \int_0^t (1+\tau)^{-\frac{1}{\alpha}} d\tau \le C|\xi|.$$

Taking  $g^{2\alpha} = \frac{\beta}{2(1+t)}$ , we obtain, by integrating (4.7),

$$(1+t)^{\beta} \int_{\mathbb{R}^2} |\widehat{w}|^2 \le C \left[ \int_0^t (1+\tau)^{\beta - \frac{2}{\alpha}} d\tau + \int_0^t (1+\tau)^{\beta} g^4(\tau) d\tau \right].$$

Therefore,

$$||w||_{L^2}^2 \le C(1+t)^{1-\frac{2}{\alpha}}.$$

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This completes the proof of Theorem 4.3.

We can consider lower bounds for the decay of  $\theta$  with the aid of Theorem 4.3. It is easy to see that  $\Theta$  can decay exponentially fast. For example, if  $\hat{\theta}_0 = 0$  for  $|\xi| \leq \gamma$ , then

$$\|\Theta(t)\|_{L^2}^2 = \int e^{-2|\xi|^{2\alpha}t} |\widehat{\theta}_0(\xi)|^2 \le \|\theta_0\|_{L^2}^2 e^{-2\gamma^2 t}.$$

However, for those  $\theta_0$  satisfying

(4.8) 
$$|\hat{\theta}_0(\xi)| \ge \lambda \quad \text{for} \quad |\xi| \le \gamma$$

we have the following.

PROPOSITION 4.5. Let  $\alpha \in (0,1]$  and  $\theta_0 \in L^2(\mathbb{R}^2)$  satisfy (4.8). Then if  $\Theta$  is a solution of the linear QGS equation,

$$\|\Theta(t)\|_{L^2(\mathbb{R}^2)} \ge C(1+t)^{-\frac{1}{2\alpha}},$$

where C is a constant depending only on  $\lambda$ ,  $\gamma$ , and the  $L^2$  norm of  $\theta_0$ .

As a corollary of Theorem 4.3 and Proposition 4.5, we have the following.

THEOREM 4.6. Let  $\alpha \in (0,1]$  and  $\theta_0 \in L^1(\mathbb{R}^2) \cap L^2(\mathbb{R}^2)$  satisfy (4.8). Then for a weak solution  $\theta$  of the QGS equation with data  $\theta_0$ ,

$$\|\theta(\cdot,t)\|_{L^2(\mathbb{R}^2)} \ge C(1+t)^{-\frac{1}{2\alpha}},$$

where C depends on  $\lambda, \gamma$ , and the  $L^1$  and  $L^2$  norms of  $\theta_0$ .

The following theorem reveals more detailed aspects of the higher-order correction.

THEOREM 4.7. Let  $\alpha \in (\frac{1}{2}, 1]$  and  $\delta > 0$  such that  $2\alpha - 1 - \delta \ge 0$ . Assume that  $\theta$  is a weak solution of the 2D QGS equation

$$\partial_t \theta + u \cdot \nabla \theta + \Lambda^{2\alpha} \theta = 0$$

with initial data  $\theta_0 \in L^1(\mathbb{R}^2) \cap L^2(\mathbb{R}^2)$  and that satisfies

(4.9) 
$$\|\Lambda^{2-2\alpha+\delta}\theta(\cdot,t)\|_{L^2} \le Ct^{-\epsilon}$$

for some constant C and  $\epsilon > 0$ . Let  $\Theta$  be the solution of the linear equation with the same initial data  $\theta_0$ . Then

(4.10) 
$$\frac{\|\theta(\cdot,t)\|_{L^2}}{\|\Theta(\cdot,t)\|_{L^2}} = 1 + O(t^{-\min\{\frac{1}{2\alpha},\epsilon\}}),$$

(4.11) 
$$t^{\frac{1}{2\alpha} + \min\{\frac{1}{2\alpha}, \epsilon\}} \|\theta(\cdot, t) - \Theta(\cdot, t)\|_{L^2} = O(1).$$

*Proof.* By taking the Fourier transform of the equation for  $\theta$ 

$$\partial_t \theta + \Lambda^{2\alpha} \theta = -u \cdot \nabla \theta,$$

we obtain

$$\widehat{\theta}(\xi,t) = e^{-|\xi|^{2\alpha}t} \widehat{\theta}_0(\xi) - \int_0^t e^{-|\xi|^{2\alpha}(t-s)} \widehat{u \cdot \nabla \theta}(\xi,s) ds.$$

Then the ratio

$$\frac{\|\theta(\cdot,t)\|_{L^2}^2}{\|\Theta(\cdot,t)\|_{L^2}^2} = \frac{\|\widehat{\theta}(\cdot,t)\|_{L^2}^2}{\|\widehat{\Theta}(\cdot,t)\|_{L^2}^2} = 1 + 2\mathcal{J}(t) + \mathcal{J}^2(t),$$

where  $\mathcal{J}$  is given by

$$\mathcal{J}(t) = \frac{\int_{\mathbb{R}^2} \left| \int_0^t e^{-|\xi|^{2\alpha}(t-s)} \widehat{u \cdot \nabla \theta}(\xi, s) ds \right|^2 d\xi}{\|\Theta\|_{L^2}^2}.$$

To prove (4.10), it suffices to show that

$$\mathcal{J}(t) = O(t^{-\min\{\frac{1}{2\alpha},\epsilon\}}).$$

946

947

The difference  $w = \theta - \Theta$  satisfies

$$\partial_t w + \Lambda^{2\alpha} w = -u \cdot \nabla \theta.$$

Since  $w(x, 0) = \theta(x, 0) - \Theta(x, 0) = 0$ ,

$$\widehat{w}(\xi,t) = -\int_0^t e^{-|\xi|^{2\alpha}(t-s)} \widehat{u \cdot \nabla \theta}(\xi,s) ds,$$

$$\|w(\cdot,t)\|_{L^{2}}^{2} = \|\widehat{w}(\cdot,t)\|_{L^{2}}^{2} = \int_{\mathbb{R}^{2}} \left|\int_{0}^{t} e^{-|\xi|^{2\alpha}(t-s)} \widehat{u\cdot\nabla\theta}(\xi,s)ds\right|^{2} d\xi.$$

Thus, to prove (4.10) and (4.11), we need only to estimate the integral

$$I \equiv \int_{\mathbb{R}^2} \left| \int_0^t e^{-|\xi|^{2\alpha} (t-s)} \widehat{u \cdot \nabla \theta}(\xi, s) ds \right|^2 d\xi.$$

To this end, we divide the integral I into the following two parts:

$$II = \int_{\mathbb{R}^2} \left| \int_0^{t/2} \cdots \right|^2 d\xi \quad \text{and} \quad III = \int_{\mathbb{R}^2} \left| \int_{t/2}^t \cdots \right|^2 d\xi.$$

Since  $\nabla \cdot u = 0$ ,  $\widehat{u \cdot \nabla \theta} = i \xi \cdot \widehat{u \theta}$  and we obtain, by setting  $\eta = t^{\frac{1}{2\alpha}} \xi$ ,

$$II = t^{-\frac{2}{\alpha}} \int_{\mathbb{R}^2} e^{-2|\eta|^{2\alpha}} \left| \int_0^{t/2} e^{\frac{s}{t}|\eta|^2} \eta \cdot \widehat{u\theta}(\eta t^{-\frac{1}{2\alpha}}, s) ds \right|^2 d\eta.$$

Since

$$\|\widehat{u\theta}(\cdot,s)\|_{L^{\infty}} \le \|u\theta(\cdot,s)\|_{L^{1}} \le \|u(\cdot,s)\|_{L^{2}} \|\theta(\cdot,s)\|_{L^{2}} \le C \|\theta(\cdot,s)\|_{L^{2}}^{2},$$

we have the bound

$$II \le Ct^{-\frac{2}{\alpha}} \int_{\mathbb{R}^2} |\eta|^2 e^{-\frac{7}{4}|\eta|^2} \left[ \int_0^\infty \|\theta(\cdot,s)\|_{L^2}^2 ds \right]^2 d\eta$$
$$\le Ct^{-\frac{2}{\alpha}} \left( \int_{\mathbb{R}^2} |\eta|^2 e^{-\frac{7}{4}|\eta|^2} d\eta \right) \|\theta\|_{L^2([0,\infty);L^2)}^4.$$

The estimate of *III* seems tricky. Intuitively, the idea is to split the whole derivative  $\nabla$  into two fractional parts  $\Lambda^{2\alpha-1-\delta}$  and  $\Lambda^{2-2\alpha+\delta}$ :

$$III = \int_{\mathbb{R}^2} \left| \int_{t/2}^t e^{-|\xi|^{2\alpha} (t-s)} \widehat{u \cdot \nabla \theta}(\xi, s) ds \right|^2 d\xi$$

$$\leq \int_{\mathbb{R}^2} e^{-2|\xi|^{2\alpha}t} |\xi|^{2(2\alpha-1-\delta)} \sup_{t/2 \leq s \leq t} |u \cdot \widehat{\Lambda^{2-2\alpha+\delta}\theta}|^2(\xi,s) \left[ \int_{t/2}^t e^{s|\xi|^{2\alpha}} ds \right]^2 d\xi$$

Using the assumption (4.9), we obtain

$$\|u\cdot\widehat{\Lambda^{2-2\alpha}+\delta}\theta|(\xi,s)\leq \|u\cdot\widehat{\Lambda^{2-2\alpha}+\delta}\theta(\cdot,s)\|_{L^\infty}$$

$$\leq \|(u \cdot \Lambda^{2-2\alpha+\delta}\theta)(\cdot,s)\|_{L^1} \leq C \|u(\cdot,s)\|_{L^2} \|\Lambda^{2-2\alpha+\delta}\theta(\cdot,s)\|_{L^2} \leq Cs^{-\frac{1}{2\alpha}-\epsilon},$$

where C is a constant. Therefore

$$III \le Ct^{-\frac{1}{\alpha} - 2\epsilon} \int_{\mathbb{R}^2} |\xi|^{-2-\delta} (1 - e^{-\frac{1}{2}|\xi|^{2\alpha}t})^2 d\xi \le Ct^{-\frac{1}{\alpha} - 2\epsilon}.$$

Combining the estimates for II and III, we conclude that

$$I \equiv \int_{\mathbb{R}^2} \left| \int_0^t e^{-|\xi|^{2\alpha}(t-s)} \widehat{u \cdot \nabla \theta}(\xi, s) ds \right|^2 d\xi \le C t^{-\frac{1}{\alpha} - \min\{\frac{1}{\alpha}, 2\epsilon\}},$$

and (4.10), (4.11) are therefore established.

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